

15. A method of providing localized haptic feedback, the method comprising the acts of:

generating a selection signal in response to a user input proximate a first contact location of an input surface; inducing a first vibration at the first contact location in response to the selection signal; and inducing a second vibration at one or more other contact locations on the input surface, the second vibration configured to suppress propagating vibrations from the first vibration.

16. The method of claim **15**, further comprising the act of inducing a third vibration at a third contact location on the input surface, the third vibration configured to suppress propagating vibrations from at least the first vibration.

17. The method of claim **15**, wherein the propagating vibrations comprise a first waveform having a first amplitude and phase, and wherein the second vibration comprises a second waveform having an amplitude and phase configured to suppress the propagating vibrations.

18. The method of claim **15**, wherein act of inducing a canceling vibration comprises:

retrieving waveform data from a memory associated with the haptic feedback system; and generating at least one waveform based on the retrieved waveform data to induce the canceling vibration.

19. A machine-readable medium encoded with instructions that, when executed by one or more processors, perform operations comprising:

receiving a user input at a first contact location of an input surface, and generating an input signal in response to the user input, the input surface comprising a plurality of contact locations having a respective vibration actuator in operative coupling to the input surface;

inducing a first vibratory response at the first contact location through actuation of a vibration actuator at such location;

inducing a second vibratory response at a second contact location through actuation of a vibration actuator at such location, the second vibratory response configured to provide destructive interference to vibratory crosstalk at the second location, the vibratory crosstalk resulting from vibrations traveling through the input surface to the second contact location as a result of the first induced vibratory response.

20. The machine-readable medium of claim **19**, wherein the second vibratory response is of generally opposite amplitude and phase to the vibratory crosstalk at the second contact location.

21. The machine-readable medium of claim **19**, wherein the second vibratory response is induced through reference to data representative of a predetermined waveform.

22. The machine-readable medium of claim **19**, wherein the first vibratory response and the second vibratory response are each induced in reference to the input signal.

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